

# Basic Information

## Constants and units

$$\begin{aligned}
c &= 299\,792\,458 \text{ m s}^{-1} \\
&\approx 3 \times 10^8 \text{ m s}^{-1} \\
h &= 6.626 \times 10^{-34} \text{ Js} \\
\hbar &= \frac{h}{2\pi} = 1.055 \times 10^{-34} \text{ Js} \\
N_A &= 6.022 \times 10^{23} \text{ mol}^{-1} \\
k_B &= 1.381 \times 10^{-23} \text{ JK}^{-1} \\
&= 1.381 \times 10^{-16} \text{ g cm}^2 \text{s}^{-2} \text{ K}^{-1} \\
R &= 8.3145 \text{ JK}^{-1} \text{ mol}^{-1} \\
&= 0.082\,06 \text{ L atm mol}^{-1} \text{ K}^{-1} \\
101.3 \text{ J} &= 1 \text{ L atm} \\
&= 0.083\,145 \text{ L bar mol}^{-1} \text{ K}^{-1} \\
m_{e^-} &= 9.109 \times 10^{-31} \text{ kg} \\
e &= 1.602 \times 10^{-19} \text{ C} \\
m_{p^+} &= 1.673 \times 10^{-27} \text{ kg} \\
m_{n^0} &= 1.675 \times 10^{-27} \text{ kg} \\
a_0 &= 4\pi\epsilon_0\hbar^2/m_e e^2 \\
&= 0.5292 \times 10^{-10} \text{ m} \\
\epsilon_0 &= 8.8542 \times 10^{-12} \text{ C}^2 \text{ N}^{-1} \text{ m}^{-2} \\
\gamma_{1H} &= 2.675\,221 \times 10^8 \text{ s}^{-1} \text{ T}^{-1} \\
&= 42.577 \text{ MHz T}^{-1} \\
R_H &= 1.097 \times 10^5 \text{ cm}^{-1} \\
1 \text{ N} &= 1 \text{ kg m s}^{-2} \\
1 \text{ J} &= 1 \text{ N m} = 1 \text{ kg m}^2 \text{ s}^{-2} \\
1000 \text{ L} &= 1 \text{ m}^3 \\
1 \text{ eV} &= 1.602 \times 10^{-19} \text{ J} \\
1 \text{ cm}^{-1} &= 1.986 \times 10^{-23} \text{ J} \\
1 \text{ u} &= 1.661 \times 10^{-27} \text{ kg}
\end{aligned}$$

## Math

$$\begin{aligned}
a \ln X &= \ln(X^a) \\
\ln A + \ln B &= \ln(AB) \\
\ln A - \ln B &= \ln \frac{A}{B} \\
\ln N! &\approx N \ln N - N \\
\ln(M - N) &\approx \ln M \text{ if } M \gg N
\end{aligned}$$

## Trigonometry

$$\begin{aligned}
\sin(2x) &= 2 \sin x \cos x \\
\cos(2x) &= \cos^2 x - \sin^2 x \\
\sin^2 x &= \frac{1 - \cos 2x}{2} \\
\cos^2 x &= \frac{1 + \cos 2x}{2} \\
\sin^2 x + \cos^2 x &= 1 \\
\sin x \sin y &= \frac{1}{2} [\cos(x - y) - \cos(x + y)] \\
\cos x \cos y &= \frac{1}{2} [\cos(x - y) + \cos(x + y)] \\
\sin x \cos y &= \frac{1}{2} [\sin(x + y) + \sin(x - y)]
\end{aligned}$$

## Determinants

$$\begin{aligned}
\begin{vmatrix} a & b \\ c & d \end{vmatrix} &= ad - bc \\
\psi(1, 2, 3, \dots, n) &= \frac{1}{\sqrt{n!}} \begin{vmatrix} u_1(1) & u_2(1) & \cdots & u_n(1) \\ u_1(2) & u_2(2) & \cdots & u_n(2) \\ \vdots & \vdots & \ddots & \vdots \\ u_1(n) & u_2(n) & \cdots & u_n(n) \end{vmatrix}
\end{aligned}$$

## Integrals

$$\int_{-\infty}^{+\infty} f(x) dx = 0 \text{ for odd } f(x)$$

$$f(-x) = -f(x) \text{ for odd } f(x)$$

$$\int_{-\infty}^{+\infty} f(x) dx = 2 \int_0^{+\infty} f(x) dx \text{ for even } f(x)$$

$$f(-x) = f(x) \text{ for even } f(x)$$

$$\int \sin(ax) dx = -\frac{1}{a} \cos(ax)$$

$$\int \cos(ax) dx = \frac{1}{a} \sin(ax)$$

$$\int \sin^2(ax) dx = \frac{x}{2} - \frac{\sin(2ax)}{4a}$$

$$\int \cos^2(ax) dx = \frac{x}{2} + \frac{\sin(2ax)}{4a}$$

$$\int x \sin^2(ax) dx = \frac{x^2}{4} - \frac{\cos(2ax)}{8a^2} - \frac{x \sin(2ax)}{4a}$$

$$\int x \cos^2(ax) dx = \frac{x^2}{4} + \frac{\cos(2ax)}{8a^2} + \frac{x \sin(2ax)}{4a}$$

$$\int x^2 \sin^2(ax) dx = \frac{x^3}{6} - \left( \frac{x^2}{4a} - \frac{1}{8a^3} \right) \sin(2ax) - \frac{x}{4a^2} \cos(2ax)$$

$$\int x^2 \cos^2(ax) dx = \frac{x^3}{6} + \left( \frac{x^2}{4a} - \frac{1}{8a^3} \right) \sin(2ax) + \frac{x}{4a^2} \cos(2ax)$$

$$\int_0^{\infty} e^{-ax^2} dx = \left( \frac{\pi}{4a} \right)^{1/2}$$

$$\int_0^{\infty} x^{2n} e^{-ax^2} dx = \frac{1 \cdot 3 \cdot 5 \cdots (2n-1)}{2^{n+1} a^n} \sqrt{\frac{\pi}{a}}$$

$$\int_0^{\infty} x^{2n+1} e^{-ax^2} dx = \frac{n!}{2a^{n+1}}$$

$$\int_0^{\infty} x^n e^{-ax} dx = \frac{n!}{a^{n+1}}$$

# Thermodynamics and Kinetics

## Thermodynamics

$$\begin{aligned}\Delta U &= w + q \\ w &= -p_{ext}\Delta V \\ w_{\text{iso-T}} &= - \int_{V_1}^{V_2} \frac{nRT}{V} dV = -nRT \ln \frac{V_2}{V_1} \\ H &= U + pV \\ \Delta H &= q_p = \int dH = \int C_p(T) dT \\ C_V &= \left( \frac{\partial U}{\partial T} \right)_V; C_p = \left( \frac{\partial H}{\partial T} \right)_p \\ C_p &= C_V + nR \\ \Delta S &= \frac{q_{rev}}{T} = nR \ln \frac{V_2}{V_1} + C_V \ln \frac{T_2}{T_1} \\ \Delta S &= \int \frac{C_p}{T} dT + \sum_i \frac{\Delta_{trs}H}{T} \\ \frac{S}{R} &= \frac{7}{2} + \ln \left[ \left( \frac{2\pi m k_B T}{h^2} \right)^{3/2} \frac{V}{N} \right] + \ln \left[ \frac{T}{\sigma \theta_{rot}} \right] \dots \\ \dots &+ \frac{\theta_{vib}}{T} \left( \frac{1}{e^{\theta_{vib}/T} - 1} \right) - \ln \left[ 1 - e^{-\theta_{vib}/T} \right] + \ln [g_{e1}] \dots \\ \frac{p_2}{p_1} &= \left( \frac{V_1}{V_2} \right)^\gamma \\ V_2 &= \frac{V_1}{\gamma} \left[ \gamma - 1 + \frac{p_1}{p_2} \right] \\ \gamma &= C_p/C_V \\ A &= U - TS \\ G &= U - TS + pV = H - TS \\ \Delta G^\circ &= -RT \ln K_{eq} \\ \Delta G &= \Delta G^\circ + RT \ln Q \\ dU &= TdS - pdV; \left( \frac{\partial T}{\partial V} \right)_S = - \left( \frac{\partial p}{\partial S} \right)_V \\ dH &= TdS + Vdp; \left( \frac{\partial T}{\partial p} \right)_S = \left( \frac{\partial V}{\partial S} \right)_p \\ dA &= -SdT - pdV; \left( \frac{\partial S}{\partial V} \right)_T = \left( \frac{\partial p}{\partial T} \right)_V \\ dG &= -SdT + Vdp; \left( \frac{\partial S}{\partial p} \right)_T = - \left( \frac{\partial V}{\partial T} \right)_p \\ \left( \frac{\partial (\Delta G/T)}{\partial T} \right)_p &= -\frac{\Delta H}{T^2}\end{aligned}$$

## Statistical Mechanics

$$\begin{aligned}\frac{a_n}{a_m} &= e^{-\beta \Delta E}; \beta = \frac{1}{k_B T} \\ p_j &= \frac{e^{-\beta E_j}}{\sum_i e^{-\beta E_i}} = \frac{e^{-\beta E_j}}{Q} \\ Q(N, V, \beta) &= \sum_i e^{-\beta E_i} = \frac{q^N}{N!} \\ q_{trans} &= \left( \frac{2\pi m k_B T}{h^2} \right)^{3/2} V \\ q_{rot} &\approx \frac{T}{\sigma \theta_{ROT}}; \theta_{ROT} = \frac{\hbar^2}{2Ik_B}, I = \mu r^2 \\ q_{vib} &= \frac{e^{-\theta_{VIB}/2T}}{1 - e^{-\theta_{VIB}/T}} \\ \theta_{VIB} &= \frac{\hbar \left( \frac{k}{\mu} \right)^{1/2}}{k_B} = \frac{h\nu}{k_B} \\ \langle E \rangle &= U = - \left( \frac{\partial \ln Q}{\partial \beta} \right)_{N,V} \\ &= k_B T^2 \left( \frac{\partial \ln Q}{\partial T} \right)_{N,V} \\ \langle p \rangle &= \frac{1}{Q\beta} \left( \frac{\partial Q}{\partial V} \right)_{N,T} = k_B T \left( \frac{\partial \ln Q}{\partial V} \right)_{N,T} \\ S &= k_B \ln W = -k_B \sum_i p_i \ln p_i \\ S &= k_B T \left( \frac{\partial \ln Q}{\partial T} \right)_{N,V} + k_B \ln Q \\ H &= k_B T \left[ T \left( \frac{\partial \ln Q}{\partial T} \right)_{N,V} + V \left( \frac{\partial \ln Q}{\partial V} \right)_{N,T} \right] \\ A &= -k_B T \ln Q \\ G &= k_B T \left[ V \left( \frac{\partial \ln Q}{\partial V} \right)_{N,T} - \ln Q \right] \\ \mu &= -RT \left( \frac{\partial \ln Q}{\partial N} \right)_{V,T} \\ W(M, N) &= \frac{M!}{N!(M-N)!}\end{aligned}$$

## Equilibrium

$$\begin{aligned}\mu &= \left( \frac{\partial G}{\partial n} \right)_{p,T} \\ \frac{dp}{dT} &= \frac{\Delta S}{\Delta V} \\ &= \frac{\Delta H}{T\Delta V} \\ \ln \frac{p_2}{p_1} &= -\frac{\Delta_{vap}H}{R} \left( \frac{1}{T_2} - \frac{1}{T_1} \right) \\ \ln \frac{K_p(T_2)}{K_p(T_1)} &= -\frac{\Delta_{rxn}H}{R} \left( \frac{1}{T_2} - \frac{1}{T_1} \right) \\ \Delta_{rxn}G^\circ(T) &= -RT \ln K_p(T) \\ \Delta_{rxn}G &= \Delta_{rxn}G^\circ + RT \ln Q \\ Q &= \frac{p_Y^{\nu_Y} p_Z^{\nu_Z} \cdots}{p_A^{\nu_A} p_B^{\nu_B} \cdots} \\ K_p &= \left( \frac{p_Y^{\nu_Y} p_Z^{\nu_Z} \cdots}{p_A^{\nu_A} p_B^{\nu_B} \cdots} \right)_{eq} \\ K_c &= \left( \frac{c_Y^{\nu_Y} c_Z^{\nu_Z} \cdots}{c_A^{\nu_A} c_B^{\nu_B} \cdots} \right)_{eq} \\ &= \frac{\left(\frac{q_Y}{V}\right)^{\nu_Y} \left(\frac{q_Z}{V}\right)^{\nu_Z} \cdots}{\left(\frac{q_A}{V}\right)^{\nu_A} \left(\frac{q_B}{V}\right)^{\nu_B} \cdots} \\ K_p &= K_c \left( \frac{c^\circ}{p^\circ} RT \right)^{\nu_Y + \nu_Z + \cdots - \nu_A - \nu_B - \cdots} \\ \frac{q}{V} &= \frac{q_{trans}}{V} q_{rot} q_{vib} q_{elec} \\ &= \frac{q^\circ}{V} e^{D_0/k_B T} \\ q_{vib} q_{elec} &= \frac{1}{1 - e^{-\theta/T}} \cdot g \cdot e^{D_0/RT} \\ \frac{q^\circ}{V} &= \frac{N_A p^\circ}{RT} e^{-(G^\circ - H_0^\circ)/RT}\end{aligned}$$

## Kinetics

$$\begin{aligned}k &= Ae^{-\frac{E_a}{RT}} \\ t_{1/2} &= \frac{\ln 2}{k} \text{ first-order only} \\ v(t) &= -\frac{1}{a} \frac{d[A]}{dt} = \dots \\ &= -\frac{1}{V} \frac{d\xi}{dt} \\ K_c &= \frac{k_1}{k_{-1}} = \frac{[B]_{eq}}{[A]_{eq}} \\ k &= \frac{k_B T}{hc^\circ} e^{\frac{\Delta f_S^\circ}{R}} e^{-\frac{\Delta f_H^\circ}{RT}} \\ &= \frac{k_B T}{hc^\circ} e^2 \cdot e^{\frac{\Delta f_S^\circ}{R}} e^{-\frac{E_a}{RT}} \\ E_a &= \Delta f H^\circ + 2RT\end{aligned}$$

## Kinetic Molecular Theory

$$\begin{aligned}\sigma &= \pi d^2 \\ \rho &= \left( \frac{p N_A}{R T} \right) \\ z_{12} &= \frac{N_2}{V} \sigma \left( \frac{8kT}{\pi\mu} \right)^{1/2} \\ \lambda &= \frac{1}{\sqrt{2\rho\sigma}} \\ Z_{12} &= \rho_1 \rho_2 \sigma \left( \frac{8kT}{\pi\mu} \right)^{1/2} \\ P(v) &= 4\pi \left( \frac{M}{2\pi R T} \right)^{3/2} v^2 e^{-Mv^2/2RT} \\ \langle v \rangle &= \left( \frac{8RT}{\pi M} \right)^{1/2} \\ v_{rms} &= \left( \frac{3RT}{M} \right)^{1/2} \\ v_{mp} &= \left( \frac{2RT}{M} \right)^{1/2}\end{aligned}$$

## Molecular Transport

$$J(x) = -D \left[ \frac{\partial c(x)}{\partial x} \right]$$

$$\frac{\partial c(x, t)}{\partial t} = D \frac{\partial^2 c(x, t)}{\partial x^2}$$

$$D = \frac{k_B T}{f}$$

$$f_{\text{sphere}} = 6\pi\eta r$$

$$f_{\text{disk, random}} = 12\eta r$$

$$\langle r^2 \rangle_{3D}^{1/2} = \sqrt{6Dt}$$

# Quantum Mechanics and Spectroscopy

## General QM

$$E = h\nu = \frac{hc}{\lambda}$$

$$\lambda = \frac{h}{p}$$

$$\Psi(x, t) = \psi(x) e^{-i(E/\hbar)t}$$

$$\left[ -\frac{\hbar^2}{2m} \nabla^2 + V(x, t) \right] \Psi(x, t) = i\hbar \frac{\partial \Psi(x, t)}{\partial t}$$

$$\left[ -\frac{\hbar^2}{2m} \nabla^2 + V(x) \right] \psi(x) = E\psi(x)$$

$$\hat{H}\psi_n(x) = E_n\psi_n(x)$$

$$\nabla^2 = \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right)$$

$$\hat{x} = x$$

$$\hat{p}_x = -i\hbar \frac{\partial}{\partial x}$$

$$\int_{-\infty}^{+\infty} \Psi^*(x, t) \Psi(x, t) dx = 1$$

$$\langle a \rangle = \frac{\int_{-\infty}^{+\infty} \Psi^*(x, t) \hat{A} \Psi(x, t) dx}{\int_{-\infty}^{+\infty} \Psi^*(x, t) \Psi(x, t) dx}$$

$$[\hat{A}, \hat{B}] = \hat{A}\hat{B} - \hat{B}\hat{A}$$

$$[\hat{A}, \hat{B}] = - [\hat{B}, \hat{A}]$$

$$\Delta p \Delta x \geq \frac{\hbar}{2}$$

$$E_{variational} = \frac{\int \Phi^* \hat{H} \Phi d\tau}{\int \Phi^* \Phi d\tau} \geq E_0$$

## Particle in a Box

$$\psi_{1D}(x) = \left(\frac{2}{a}\right)^{1/2} \sin\left(\frac{n\pi x}{a}\right); n = 1, 2, 3 \dots$$

$$E_n = \frac{\hbar^2 n^2}{8ma^2}$$

$$\psi_{3D}(x, y, z) = \left(\frac{8}{abc}\right)^{1/2} \sin\left(\frac{n_x \pi x}{a}\right) \sin\left(\frac{n_y \pi y}{b}\right) \sin\left(\frac{n_z \pi z}{c}\right)$$

$$E = \frac{\hbar^2}{8m} \left( \frac{n_x^2}{a^2} + \frac{n_y^2}{b^2} + \frac{n_z^2}{c^2} \right)$$

## Harmonic Oscillator

$$V(x) = \frac{1}{2} kx^2$$

$$x_{cm} = \frac{m_1 x_1 + m_2 x_2}{m_1 m_2}$$

$$\mu = \frac{m_1 m_2}{m_1 + m_2}$$

$$\hat{H} = \left[ -\frac{\hbar^2}{2\mu} \frac{\partial^2}{\partial x^2} + \frac{1}{2} kx^2 \right]$$

$$\psi_v(x) = A_v H_v \left( \alpha^{1/2} x \right) e^{-\frac{1}{2}\alpha x^2}$$

$$\psi_0(x) = \left( \frac{\alpha}{\pi} \right)^{1/4} e^{-\frac{1}{2}\alpha x^2}$$

$$\psi_1(x) = \left( \frac{4\alpha^3}{\pi} \right)^{1/4} x e^{-\frac{1}{2}\alpha x^2}$$

$$\psi_2(x) = \left( \frac{\alpha}{4\pi} \right)^{1/4} (2\alpha x^2 - 1) e^{-\frac{1}{2}\alpha x^2}$$

$$\alpha = \sqrt{\frac{k\mu}{\hbar^2}}$$

$$E_v = \hbar \sqrt{\frac{k}{\mu}} \left( v + \frac{1}{2} \right) = h\nu \left( v + \frac{1}{2} \right); v = 0, 1, 2, 3, \dots$$

$$\nu = \frac{1}{2\pi} \sqrt{\frac{k}{\mu}} = \tilde{\nu}_c$$

## Anharmonic Oscillator

$$V(x) = D_e \left( e^{-2ax} - 2e^{-ax} \right); a = \sqrt{\frac{k}{2D_e}}$$

$$E_v = h\nu \left( v + \frac{1}{2} \right) - \frac{(h\nu)^2}{4D_e} \left( v + \frac{1}{2} \right)^2$$

$$G(v) = \tilde{\nu} \left( v + \frac{1}{2} \right) - \tilde{x}\tilde{\nu} \left( v + \frac{1}{2} \right)^2; \tilde{x} = \frac{hc\tilde{\nu}}{4D_e}$$

## Rigid Rotor

$$I = \mu r^2$$

$$L = I\omega$$

$$KE = \frac{1}{2} I \omega^2$$

$$= \frac{L^2}{2I}$$

## 2D

$$\hat{H} = -\frac{\hbar^2}{2\mu r_0^2} \frac{\partial^2}{\partial\phi^2}$$

$$\Phi_{m_l}(\phi) = \frac{1}{\sqrt{2\pi}} e^{im_l\phi}$$

$$m_l = 0, \pm 1, \pm 2, \dots$$

$$E_{m_l} = \frac{\hbar^2 m_l^2}{2I}$$

$$\hat{L}_z \Phi_{m_l}(\phi) = m_l \hbar \Phi_{m_l}(\phi)$$

## 3D

$$\hat{H} = -\frac{\hbar^2}{2\mu r_0^2} \left[ \frac{1}{\sin\theta} \frac{\partial}{\partial\theta} \left( \sin\theta \frac{\partial}{\partial\theta} \right)_{r,\phi} + \frac{1}{\sin^2\theta} \left( \frac{\partial^2}{\partial\phi^2} \right)_{r,\theta} \right] R_{nl}(r)$$

$$Y(\theta, \phi) = Y_l^{m_l}(\theta, \phi) = \Theta_l^{m_l}(\theta) \Phi_{m_l}(\phi)$$

$$E_l = \frac{\hbar^2}{2I} l(l+1)$$

$$l = 0, 1, 2, 3, \dots$$

$$m_l = -l, -(l-1), \dots, 0, \dots, (l-1), l$$

$$E_J = hc\tilde{B}J(J+1)$$

$$\tilde{B} = \frac{h}{8\pi^2 c \mu r_0^2}$$

$$\hat{L}_z Y_l^{m_l}(\theta, \phi) = m_l \hbar Y_l^{m_l}(\theta, \phi)$$

$$\hat{L}^2 Y_l^{m_l}(\theta, \phi) = \hbar^2 l(l+1) Y_l^{m_l}(\theta, \phi)$$

$$\hat{L}_{\frac{y}{z}} = -i\hbar \left( \frac{y}{z} \frac{\partial}{\partial z} - \frac{z}{y} \frac{\partial}{\partial y} \right)$$

$$\left[ \hat{L}_{\frac{x}{y}}, \hat{L}_{\frac{y}{z}} \right] = i\hbar \hat{L}_{\frac{z}{x}}$$

## Hydrogen atom

$$V(r) = -\frac{e^2}{4\pi\epsilon_0 r}$$

$$V_{eff}(r) = \frac{\hbar^2 l(l+1)}{2m_e r^2} - \frac{e^2}{4\pi\epsilon_0 r}$$

$$E_n = -\frac{m_e e^4}{8\epsilon_0^2 h^2 n^2} = -\frac{e^2}{8\pi\epsilon_0 a_0 n^2}$$

$$a_0 = \frac{\epsilon_0 h^2}{\pi m_e e^2}$$

$$n = 1, 2, 3, \dots$$

$$l = 0, 1, 2, \dots, n-1$$

$$m_l = 0, \pm 1, \pm 2, \dots, \pm l$$

## Radial functions

$$R_{nl}(r) = \dots$$

$$R_{10}(r) = 2 \left( \frac{1}{a_0} \right)^{3/2} e^{-r/a_0}$$

$$R_{20}(r) = \frac{1}{\sqrt{8}} \left( \frac{1}{a_0} \right)^{3/2} \left( 2 - \frac{r}{a_0} \right) e^{-r/2a_0}$$

$$R_{21}(r) = \frac{1}{\sqrt{24}} \left( \frac{1}{a_0} \right)^{3/2} \frac{r}{a_0} e^{-r/2a_0}$$

$$R_{30}(r) = \frac{2}{81\sqrt{3}} \left( \frac{1}{a_0} \right)^{3/2} \left( 27 - 18\frac{r}{a_0} + 2\frac{r^2}{a_0^2} \right) e^{-r/3a_0}$$

$$R_{31}(r) = \frac{4}{81\sqrt{6}} \left( \frac{1}{a_0} \right)^{3/2} \left( 6\frac{r}{a_0} - \frac{r^2}{a_0^2} \right) e^{-r/3a_0}$$

$$R_{32}(r) = \frac{4}{81\sqrt{30}} \left( \frac{1}{a_0} \right)^{3/2} \frac{r^2}{a_0^2} e^{-r/3a_0}$$

$$P_{nl}(r) dr = R_{nl}^2(r) r^2 dr$$

## Full wavefunctions

$$\begin{aligned} \psi_{nlm_l}(r, \theta, \phi) &= R_{nl}(r) Y_l^{m_l}(\theta, \phi) \\ &= R_{nl}(r) Y_{s,p,d,f,\dots,x,y,z}(\theta, \phi) \end{aligned}$$

## Term Symbols

$$\begin{aligned} & {}^{2S+1}L_J \\ L &= \sum_i l_i, M_L = \sum_i l_{z,i} \\ S &= \sum_i s_i, M_S = \sum_i s_{z,i} \\ J &= L + S, L + S - 1, \dots, |L - S| \\ & {}^{2S+1}\Lambda_\Omega \text{ for molecules} \end{aligned}$$

## Spherical Harmonics

### Complex

$$\begin{aligned} Y_l^{m_l}(\theta, \phi) &= \dots \\ Y_0^0(\theta, \phi) &= \left(\frac{1}{4\pi}\right)^{1/2} \\ Y_1^0(\theta, \phi) &= \left(\frac{3}{4\pi}\right)^{1/2} \cos \theta \\ Y_1^{\pm 1}(\theta, \phi) &= \mp \left(\frac{3}{8\pi}\right)^{1/2} \sin \theta e^{\pm i\phi} \\ Y_2^0(\theta, \phi) &= \left(\frac{5}{16\pi}\right)^{1/2} (3 \cos^2 \theta - 1) \\ Y_2^{\pm 1}(\theta, \phi) &= \mp \left(\frac{15}{8\pi}\right)^{1/2} \sin \theta \cos \theta e^{\pm i\phi} \\ Y_2^{\pm 2}(\theta, \phi) &= \left(\frac{15}{32\pi}\right)^{1/2} \sin^2 \theta e^{\pm 2i\phi} \end{aligned}$$

### Real

$$\begin{aligned} p_z &= Y_1^0 = \sqrt{\frac{3}{4\pi}} \cos \theta \\ p_x &= \frac{-1}{\sqrt{2}} (Y_1^1 - Y_1^{-1}) = \sqrt{\frac{3}{4\pi}} \sin \theta \cos \phi \\ p_y &= \frac{-1}{\sqrt{2}i} (Y_1^1 + Y_1^{-1}) = \sqrt{\frac{3}{4\pi}} \sin \theta \sin \phi \\ d_{z^2} &= Y_2^0 = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1) \\ d_{xz} &= \frac{-1}{\sqrt{2}} (Y_2^1 - Y_2^{-1}) = \sqrt{\frac{15}{4\pi}} \sin \theta \cos \theta \cos \phi \\ d_{yz} &= \frac{-1}{\sqrt{2}i} (Y_2^1 + Y_2^{-1}) = \sqrt{\frac{15}{4\pi}} \sin \theta \cos \theta \sin \phi \\ d_{xy} &= \frac{1}{\sqrt{2}i} (Y_2^2 - Y_2^{-2}) = \sqrt{\frac{15}{16\pi}} \sin^2 \theta \sin 2\phi \\ d_{x^2-y^2} &= \frac{1}{\sqrt{2}} (Y_2^2 + Y_2^{-2}) = \sqrt{\frac{15}{16\pi}} \sin^2 \theta \cos 2\phi \end{aligned}$$